

FIG. 5

WIRC Config Robot Limits Home Position Robot Velocity I/O Boards	
Home Position Robot Velocity 110 Bosins	
Motor/Axis 3	Robot: 1
	9 / 360°
 ♣ Abs+ ♣ + ♠ Abs- 120° 	-110°
Absolute Positive: 170 Absolute Negative: -170 Positive Offset: 50 Negative Offset: 60	
OK Cancel	

FIG. 6

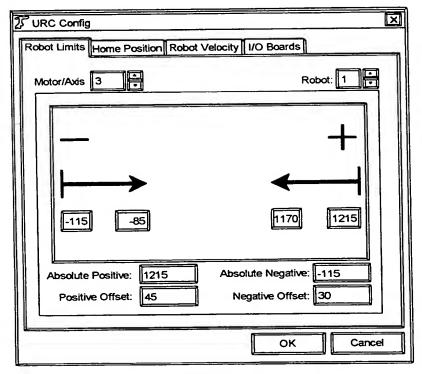


FIG. 7

